



Dr. Philip Koopman

Whirlwind Intro to UL 4600 Safety Standard for Autonomous Vehicles

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**Carnegie
Mellon
University**



@PhilKoopman



**EDGE CASE
RESEARCH**

- Self Driving Car safety case assessment
- Underwriters Laboratories
 - Non-profit Standards Development Organization
 - Standards Technical Panel:
Developers, suppliers, academia, government, insurance, assessors, international reps., ...
 - UL 4600 issued April 2020 for light vehicles
 - UL 4600 version 2 kickoff summer 2020
 - UL 4600-2 for trucks kickoff summer 2020
- Goal based approach:
 - Works with other standards to avoid gaps in safety approaches



■ Safety claims

- “What does safe mean?”

■ Arguments

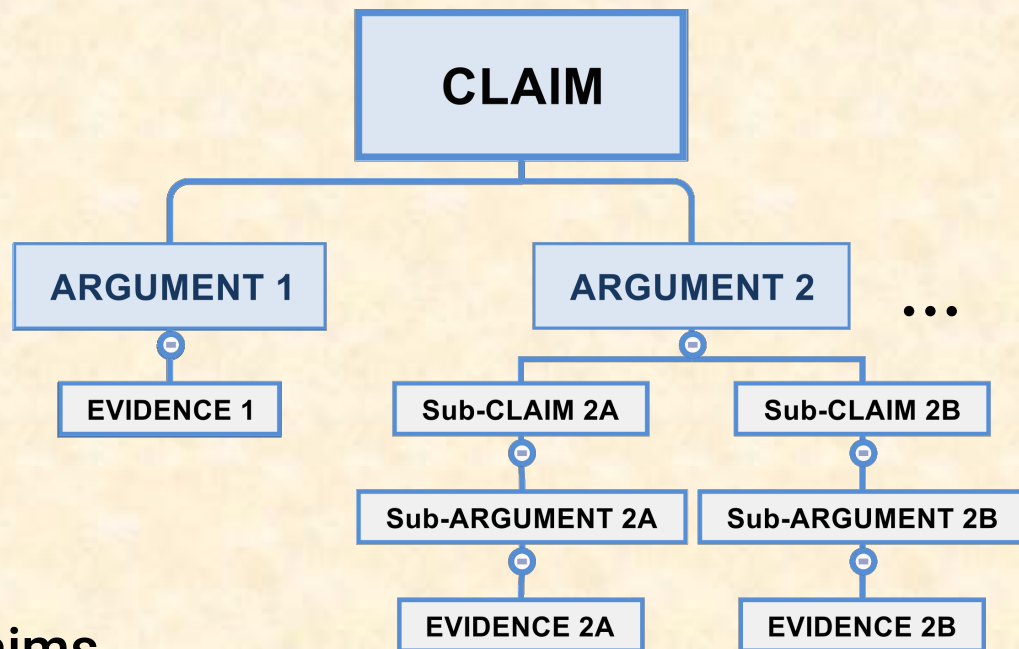
- “Why do we think it’s safe?”

■ Evidence

- “Where’s the data?”

■ 4600 helps ensure:

- Evidence → Arguments → Claims
- Seeded hazard lists: [#DidYouThinkofThat?](#)
- System level approach to safety





Is it safe to drive now?

■ Driving:

- Functional safety & SOTIF
- Software safety in general
- Machine learning and autonomy

■ There is no “Captain” in charge:

- **Lifecycle:** deployment, operation, incidents, maintenance, ...
- **Infrastructure:** vehicle, roads, data networks, cloud computing, ...
- **Road users:** pedestrians, light mobility, emergency responders, ...
- **Environment:** Operational Design Domain (ODD) violations
- ... and more ...

- Post-deployment feedback is essential
- Safety Performance Indicators (SPIs)
 - Is the system's behavior safe?
 - Are assumptions in the safety case true?
 - Does field data look like we expect it to?
- Feedback loops
 - Diagnose and fix root cause of SPI alerts:
 - Testing, operational, procedural, training data, ...
 - Field feedback continually improves:
vehicle design // safety case // risk evaluation





EDGE CASE RESEARCH

WE DELIVER THE PROMISE OF AUTONOMY

<https://edge-case-research.com/ul4600/>